

Day 34

Application of frequency response  
analysis to the drone

AE353

Spring 2022

Bret1

35.329  
35.997

32.96  
33.41

33.41  
39.72

$\omega$	MAG	ANG
1	1.12	-0.45
2	1.22	-1.34
5	0.22	-2.76

7.142  
8.394

6.593

$$\dot{x} = Ax + Bu$$

$$u = u_{des} - K(x - x_{des})$$

$$x_{des} = \begin{bmatrix} q_{des} \\ 0 \end{bmatrix} = \begin{bmatrix} I \\ 0 \end{bmatrix} \begin{bmatrix} r \end{bmatrix}$$

$$\dot{x} = Ax + B(u_{des} - K(x - Mr))$$

$$= (A - BK)x + \underbrace{Bu_{des}}_{-Ax_{des} = -AMr} + BKM r$$

$$0 = Ax_{des} + Bu_{des}$$

$$-Ax_{des} = -AMr$$

$$\begin{aligned} \dot{x} &= \underbrace{A_m}_{A_m} x - \underbrace{(A - BK)M}_{B_m} r \\ y &= \underbrace{M^T}_{C_m} x \end{aligned}$$

$$\begin{aligned} \dot{x}_m &= A_m x_m + B_m u_m \\ y_m &= C_m x_m \end{aligned}$$

$$\dot{x}_m = A_m x_m + B_m u_m$$

$$y_m = C_m x_m$$

## GENERAL RESULT

transient  
(decays to zero)

$$u_m(t) = \frac{1}{2} \sin(\omega t) \Rightarrow y_m(t) = (\dots) + \frac{1}{2} |H(j\omega)| \sin(\omega t + \angle H(j\omega))$$

$$u_m(t) = \cos(\omega t) \Rightarrow y_m(t) = (\dots) + |H(j\omega)| \cos(\omega t + \angle H(j\omega))$$

magnitude

angle

a complex number

$$H(s) = C_m (sI - A_m)^{-1} B_m$$

TRANSFER FUNCTION

another complex number

$$\dot{x} = Ax + Bu$$

$$y = Cx$$

$$u = u_{des} - K(\hat{x} - x_{des})$$

$$\dot{\hat{x}} = A\hat{x} + Bu - L(C\hat{x} - y)$$

$$\dot{x} = Ax + B(u_{des} - K(\hat{x} - x_{des}))$$

$$x_{err} = \hat{x} - x$$

$$= Ax + Bu_{des} - BK(x_{err} + x) + BKx_{des}$$

$$\Rightarrow \hat{x} = x_{err} + x$$

$$= (A - BK)x - BKx_{err} + Bu_{des} + BKx_{des}$$

$$\underbrace{0 = Ax_{des} + Bu_{des}}$$

$$= (A - BK)x - BKx_{err} - (A - BK)x_{des}$$

$$= (A - BK)x - BKx_{err} - (A - BK)Mr$$

$$r = [P_y]_{des}$$

$$M = \begin{bmatrix} 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$M_r$$

$$\dot{x}_{err} = (A - LC)x_{err}$$

$$\begin{bmatrix} \dot{x} \\ \dot{x}_{err} \end{bmatrix} = \begin{bmatrix} A - BK & -BK \\ 0 & A - LC \end{bmatrix} \begin{bmatrix} x \\ x_{err} \end{bmatrix} + \begin{bmatrix} -(A - BK)M \\ 0 \end{bmatrix} r$$

$$\dot{x}_{in} = A_{in}x_{in} + B_{in}u_{in}$$

$$y_{in} = C_{in}x_{in}$$

$$[P_y] = \begin{bmatrix} M^T & 0 \end{bmatrix} \begin{bmatrix} x \\ x_{err} \end{bmatrix}$$

# Converting to/from "decibels" (dB)

absolute

dB

$m$



$20 \log_{10} m$

$10^{(\tilde{m}/20)}$



$\tilde{m}$

